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Filed:

February 17, 2004

Docket No.: 120.020US2

Title:

METHOD AND APPARATUS FOR CALIBRATING AND

MEASURING ARTERIAL COMPLIANCE AND STROKE VOLUME

## **IN THE SPECIFICATION**

Please amend the specification paragraph starting on page 7 line 16 as follows:

16 (f) using an oscillometric signal to calibrate tonometric pressure signals in a contralateral 17 arterial site. 18 19 In some embodiments, a calibrated radial pressure waveform P<sub>r</sub>(t) is derived from the 20 tonometric signal  $S_r(t)$  as follows: 21 22  $P_r(t)=(1/a_r)(S_r(t)-b_r)+p$ 23 24 where  $a_r = (S_r(t_D)-S_r(t_M))/(DBP-MBP)$ , 25  $b_r = S_r(t_M) - a_r$  MBP, and 26  $p=\rho$  gh are calibration factors, and where 27 density of blood, <u>ρ</u> = 28 acceleration to gravity, g =height difference between the oscillometric and the tonometric measurement 29 h =30 sites, and is zero if the patient is supine, MBP is oscillometric mean arterial blood pressure measured at time t<sub>M</sub>, and 31 32 DBP is oscillometric diastolic blood pressure measured at time t<sub>D</sub>.

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## Please amend the specification paragraph starting on page 11 line 2 as follows:

```
2
                  In some embodiments, two pressure points are needed for calibration. In one
 3
       such embodiment, MBP (mean arterial blood pressure) and DBP (diastolic blood
 4
       pressure) are chosen, and respective corresponding times t<sub>M</sub> and t<sub>D</sub> (shifted to the
 5
       appropriate time within a cardiac cycle, e.g., t<sub>D</sub> is shifted to the nearest pulse minimum)
 6
       are used:
 7
       S_r(t_M) = a_r MBP + b_r
 8
       S_r(t_D) = a_r DBP + b_r
 9
                 a_r = (S_r(t_D)-S_r(t_M))/(DBP-MBP)
10
                  b_r = S_r(t_M) - a_r MBP
11
       The radial artery is approximately six inches below the brachial artery. This creates a
12
       hydrostatic pressure head that can be accommodated by a further pressure head correction
13
       factor of p = \rho gh, where
14
       \rho = density of blood (= 1.03 g/cm<sup>3</sup>)
       g = acceleration to gravity (= 980 cm/sec^2)
15
       h = 6" 15 cm
16
      thus p = 1.03 \text{ g/cm}^3 980 \text{ cm/sec}^2 15 \text{ cm} = 15141 \text{ g/cm sec}^2
17
18
                   11 mm Hg if sitting (or 0 if supine)
19
       and the calibrated radial pressure waveform P<sub>r</sub>(t) is derived from the Radial Signal S<sub>r</sub>(t)
20
       as follows:
21
22
       P_r(t)=(1/a_r)(S_r(t)-b_r)+p
```

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Please amend the specification paragraph starting on page 13 line 11 to add a small space between r and t in the equation to avoid confusion with  $\pi$  (pi) as follows:

- 11 Examples
- 12  $f_{infl}(t) = k \Rightarrow n_c(t) = n_o + kt$
- (inflation)

$$f_{\text{defl}}(t) = kn_c \Rightarrow n_c(t) = n_o + (n_{\text{max}} - n_o)^{-rt}$$

14

$$f_{\text{defl}}(t) = kn_c \Rightarrow n_c(t) = n_o + (n_{\text{max}} - n_o)e^{-rt}$$

- 15 (deflation)
- 16 Constant r can be obtained for a particular oscillometric device as

$$r = -\frac{1}{t_{.01}} ln \frac{0.01n_o}{n_{max} - n_o}, t_{.01}x$$

time to 99% complete deflation.

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# Please amend the specification paragraph starting on page 15 line 1 as follows:

- 1 Using this signal, identify the peaks and nadirs of the individual pulses using a preferred
- 2 algorithm (e.g., as in the '133 '313 patent).

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## Please amend the specification paragraph starting on page 21 line 16 as follows:

We obtain stroke volume as

17

18 Equation (15): 
$$SV = \int flow(t)dt = \int A(t)v(t)dt = \sum t_{n=1,N}A[n]v[n]$$

19

- where A(t) is ascending aortic cross-sectional area as a function of time, v(t) is ascending
- 21 aortic blood velocity as a function of time, A[n] and v[n] are the corresponding sampled
- data values, t is the sampling interval, and N is the number of data points in a single
- 23 cardiac cycle. Here the integral is approximated with a simple sum, but any appropriate
- 24 numerical integration could be used to obtain higher precision (e.g. a high-order Newton-
- 25 Cotes). A[n] and v[n] are obtained as

26

- 27 Equation (16):  $A[n] = h_A[n-i]P_2[i]$
- 28 Equation (17):  $v[n] = i h_v[n-i]P_2[i]$

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# Please amend the specification paragraph starting on page 25 line 6 as follows:

- In some embodiments, the first method further includes (f) using an oscillometric
- 7 signal to calibrate tonometric pressure signals in a contralateral arterial site.
- 8 In some embodiments, a calibrated radial pressure waveform P<sub>r</sub>(t) is derived from the
- 9 tonometric signal  $S_r(t)$  as follows:
- 10  $P_r(t)=(1/a_r)(S_r(t)-b_r)+p)$
- 11 where  $a_r = (S_r(t_D)-S_r(t_M))/(DBP-MBP)$ ,
- 12  $b_r = S_r(t_M) a_r MBP$ , and
- p= $\rho$  gh are calibration factors, and where
- 14  $\rho$  = density of blood,
- g = acceleration to gravity,
- 16 h = height difference between the oscillometric and the tonometric measurement sites,
- and is zero if the patient is supine,
- MBP is oscillometric mean arterial blood pressure measured at time t<sub>M</sub>, and DBP is
- oscillometric diastolic blood pressure measured at time t<sub>D</sub>.

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# Please amend the specification paragraph starting on page 27 line 5 as follows:

5	In some embodiments, the computer derives a calibrated radial pressure
6	waveform $P_r(t)$ from the tonometric signal $S_r(t)$ as follows:
7	$P_r(t) = (1/a_r)(S_r(t)-b_r) + p$
8	where $a_r = (S_r(t_D)-S_r(t_M))/(DBP-MBP)$ ,
9	$b_r = S_r(t_M) - a_r$ MBP, and
10	$p=\underline{\rho}$ gh are calibration factors, and where
11	$\underline{\rho}$ = density of blood,
12	g = acceleration to gravity,
13	h = height difference between the oscillometric and the tonometric
14	measurement sites, and is zero if the patient is supine,
15	MBP is oscillometric mean arterial blood pressure measured at time t <sub>M</sub> , &
16	DBP is oscillometric diastolic blood pressure measured at time $t_D$ .
17	In some embodiments, the computer system further calculates a first compliance value
18	based on the calibrated radial pressure waveform, estimates end-effects of the
19	oscillometric signal, and corrects the first compliance value using the estimated end
20	effects